

# Software sensors for urban drainage and wastewater

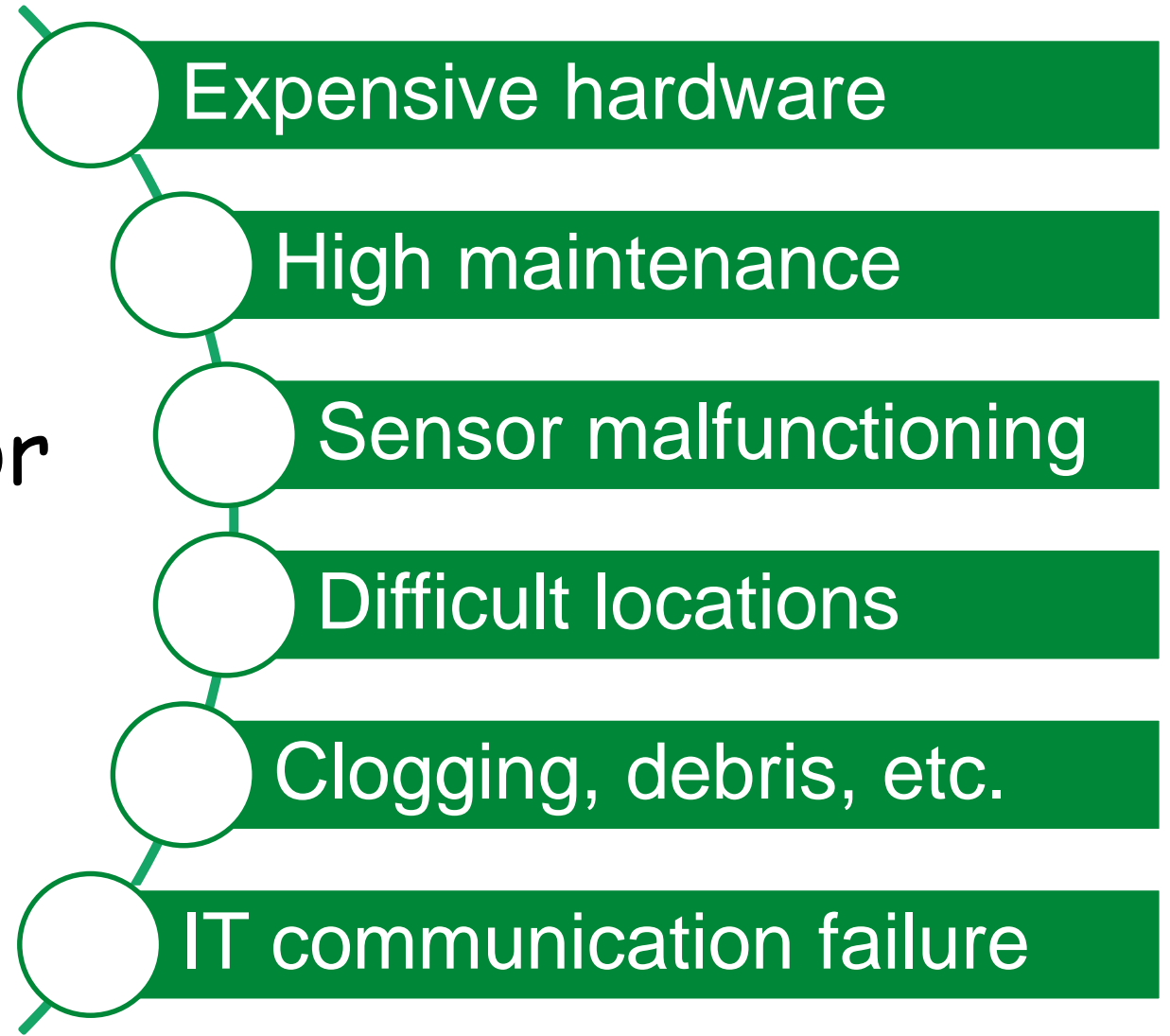
Jonas Wied Pedersen  
DTU Miljø

EVA temadag, May 20, 2021

# Smart, digitalized, real-time monitoring



Getting high-quality sensor data can be difficult!

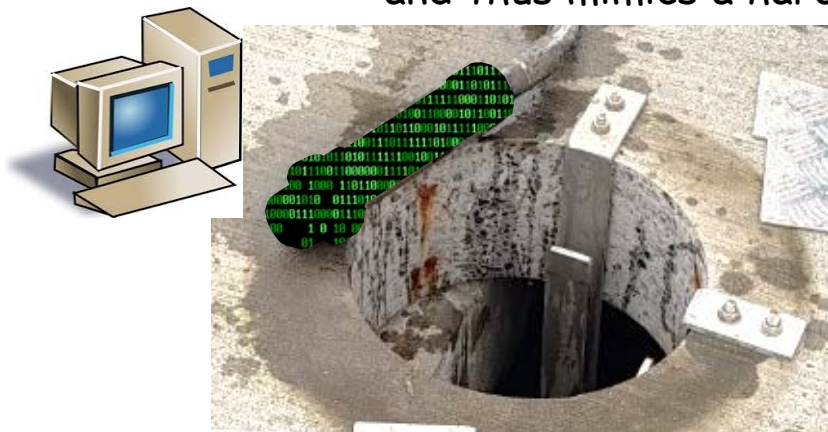


# What is a software sensor?

Hardware sensor = physical component measures a variable in the system



Software sensor = model that indirectly "measures" a variable and thus mimics a hardware sensor



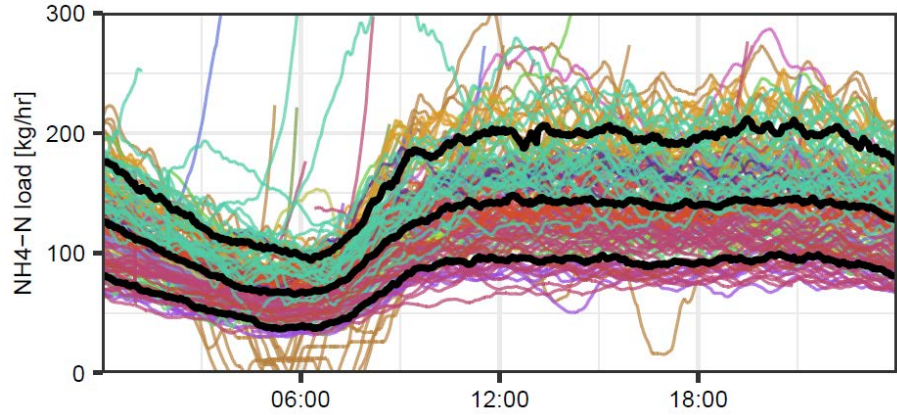
Software sensor

Virtual sensor

Just a model??



# Three software sensor examples



“Monitor”/validate water levels at upstream location

Input data: Downstream water level

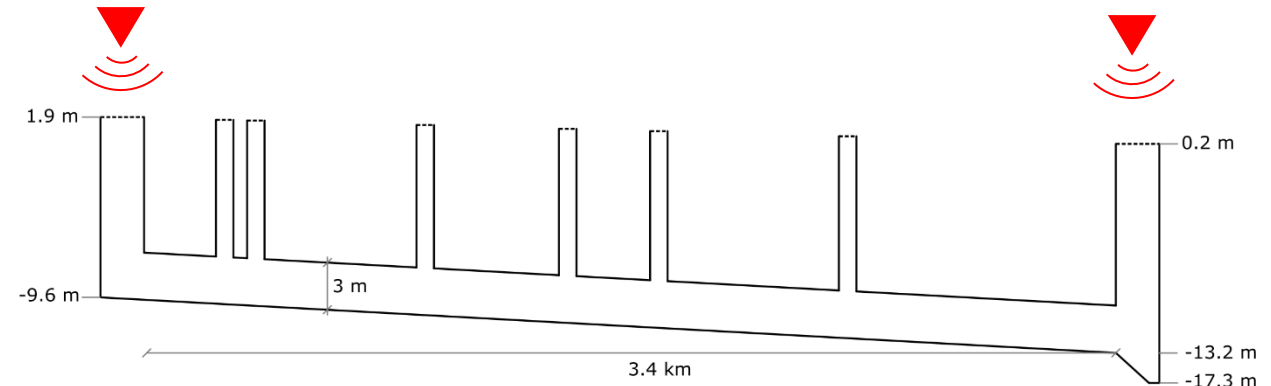
Method: Data assimilation into MU model



“Monitor”  $\text{NH}_4^+$  loads [kg/hr] at WWTP inlet

Input data: Flow

Method: Conceptual model



“Monitor”/predict water levels when sensor is unavailable

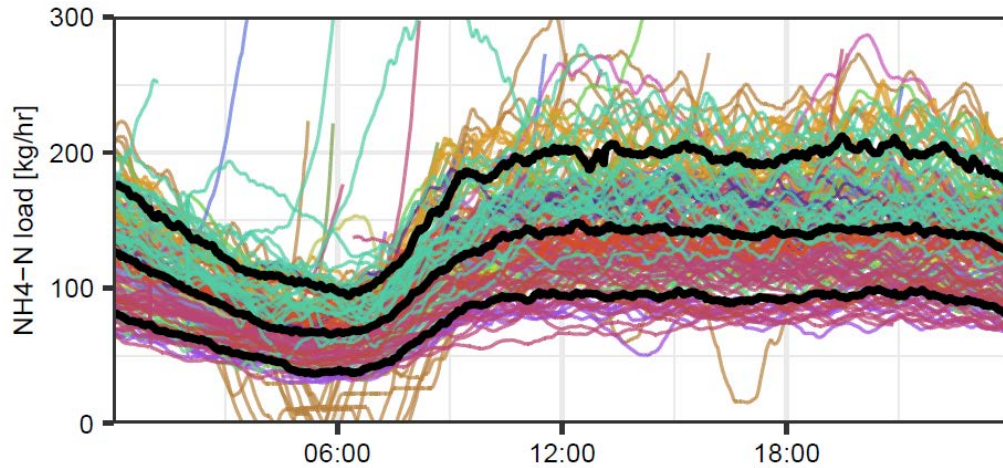
Input data: Antecedent water level, ToD, rain

Method: LSTM neural networks

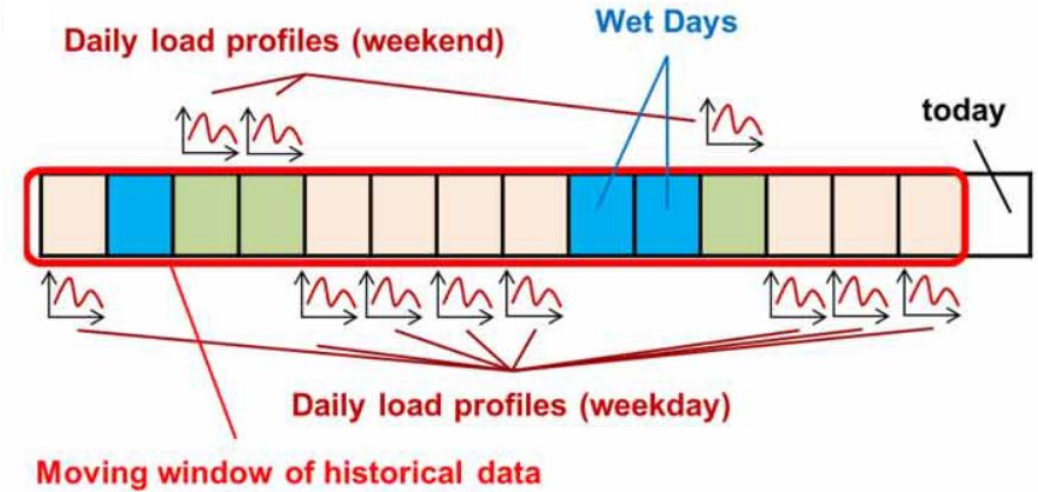


# Use flow sensor to “monitor” $\text{NH}_4^+$ concentration

Measured  $\text{NH}_4^+$  load for every day in a year



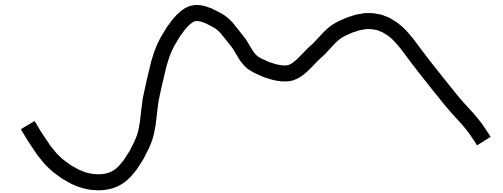
Train software sensor on all dry weekdays



Model parameters

Trained relationship for load

$$F_{\text{NH}_4^+}(t) = \mu + \sum_{k=1}^2 (\alpha_k \sin(2\pi kt) + \beta_2 \cos(2\pi kt))$$

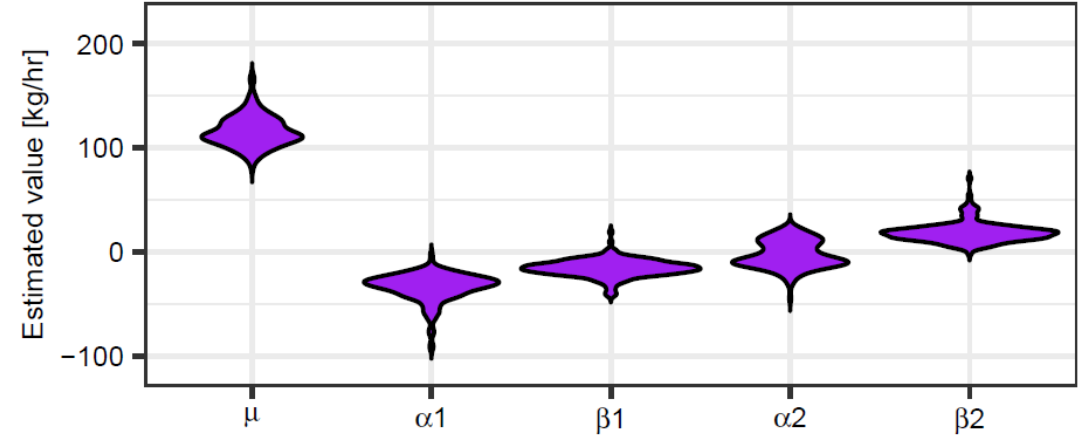
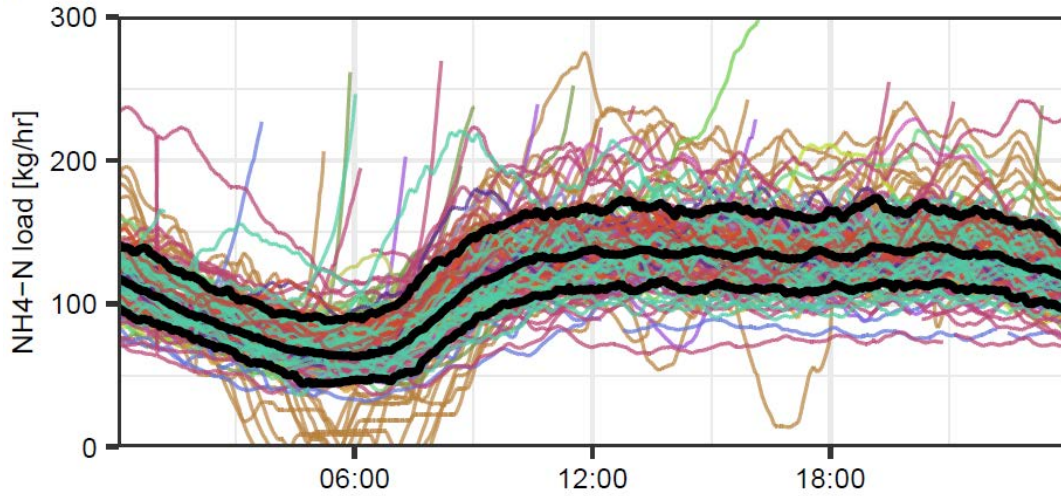


Real-time “monitored” concentration

$$s_{\text{NH}_4^+}(t) = \frac{F_{\text{NH}_4^+}(t)}{Q(t)}$$

Real-time flow observation

# Get distributions of parameters for different days

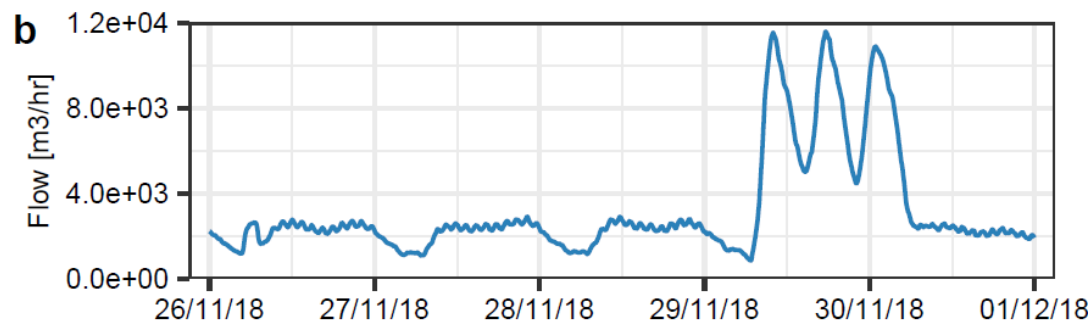


$$F_{NH_4^+}(t) = \mu + \sum_{k=1}^2 (\alpha_k \sin(2\pi kt) + \beta_k \cos(2\pi kt))$$

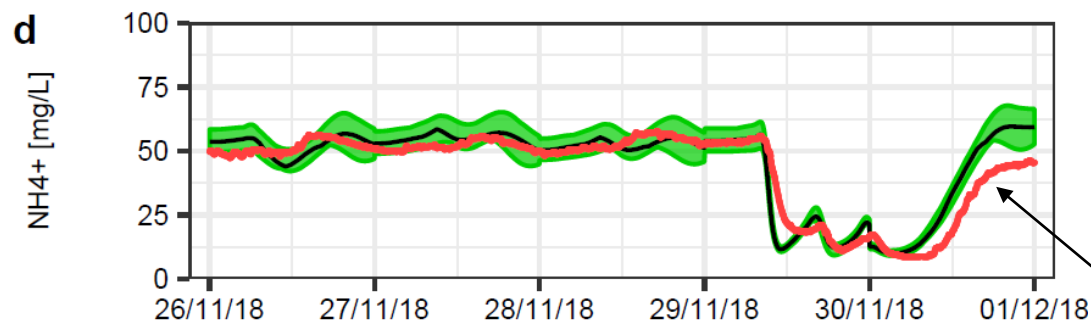
Parameter

# Example of software sensor with uncertainty estimate

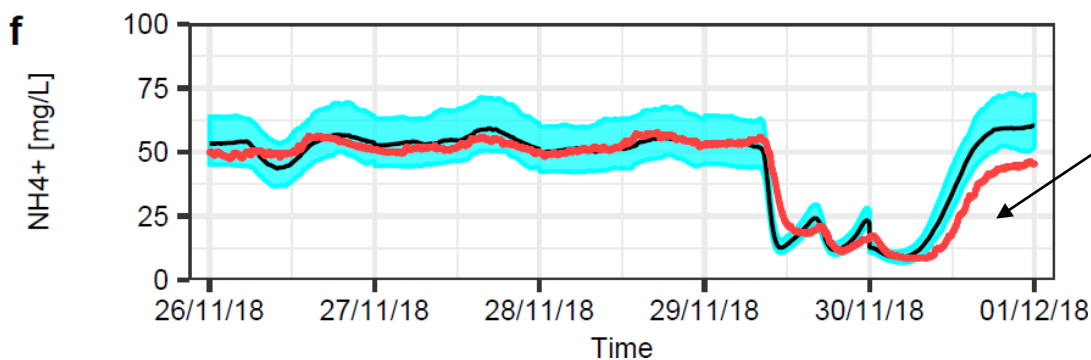
Flow measurements:



Trained on 2 weeks of data:



Trained on 16 weeks of data:

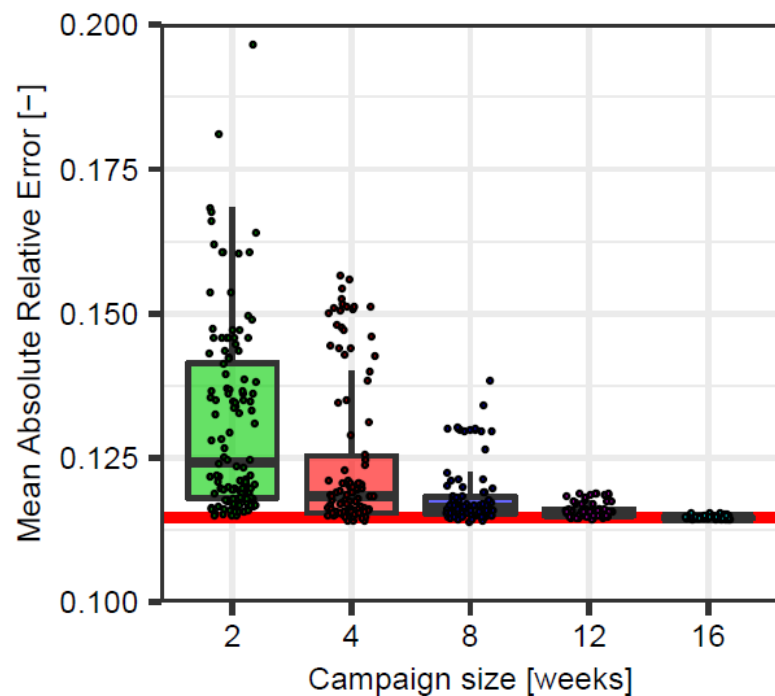


Not trained for  
rain periods

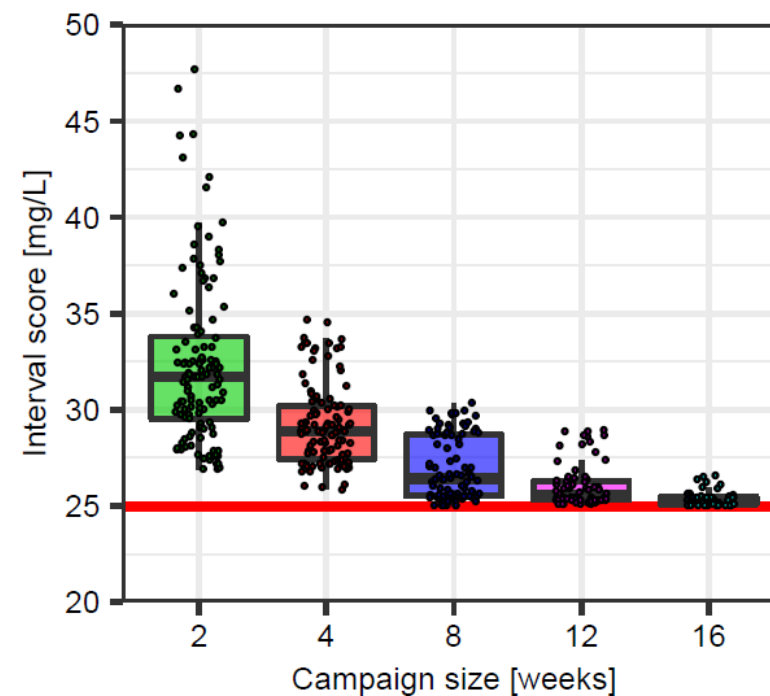


# Long-term results

~8 weeks of training data = good median estimate



~12-16 weeks of training data = good uncertainty estimate





## Reconstruction of corrupted datasets from ammonium-ISE sensors at WRRFs through merging with daily composite samples

Jonas Wied Pedersen<sup>a,\*</sup>, Laura Holm Larsen<sup>a</sup>, Carsten Thirising<sup>b</sup>, Luca Vezzaro<sup>a,c</sup>

<sup>a</sup> DTU Environment, Technical University of Denmark, Bygningstorvet, Building 115, 2800 Kgs. Lyngby, Denmark

<sup>b</sup> BIOFOS A/S, Refshalevej 250, 1432 København K, Denmark

<sup>c</sup> Krüger A/S, Veolia Water Technologies, Gladsaxevej 363, 2860 Søborg, Denmark



### ARTICLE INFO

#### Article history:

Received 25 April 2020

Revised 6 July 2020

Accepted 23 July 2020

Available online 24 July 2020

#### Keywords:

Ammonium

Ion-selective electrodes

Data merging

Software sensor

Sensor maintenance

### ABSTRACT

Long-term, continuous datasets of high quality are important for instrumentation, control, and automation efforts of wastewater resources recovery facility (WRRFs). This study presents a methodology to increase the reliability of measurements from ammonium ion-selective electrodes (ISEs). This is done by correcting corrupted ISE data with a data source that often is available at WRRFs (volume-proportional composite samples). A yearlong measurement campaign showed that the existing standard protocols for sensor maintenance might still create corrupted dataset, with poor sensor recalibrations responsible for abrupt and unrealistic jumps in the measurements. The proposed automatic correction methodology removes both recalibration jumps and signal drift by using information from composite samples that already are taken for reporting to legal authorities. Results showed that the developed methodology provided a continuous, high-quality time series without the major data quality issues of the original signal. In fact, the signal was improved for 87% of days when a reference sample was available. The effect of correcting the data before use in a data-driven software sensor was also investigated. The corrected dataset

## Evaluating the performance of a simple phenomenological model for online forecasting of ammonium concentrations at WWTP inlets

Luca Vezzaro<sup>IWA</sup>, Jonas Wied Pedersen, Laura Holm Larsen, Carsten Thirising<sup>IWA</sup>, Lene Bassø Duus and Peter Steen Mikkelsen<sup>IWA</sup>

### ABSTRACT

A simple model for online forecasting of ammonium ( $\text{NH}_4^+$ ) concentrations in sewer systems is proposed. The forecast model utilizes a simple representation of daily  $\text{NH}_4^+$  profiles and the dilution approach combined with information from online  $\text{NH}_4^+$  and flow sensors. The method utilizes an ensemble approach based on past observations to create model prediction bounds. The forecast model was tested against observations collected at the inlet of two wastewater treatment plants (WWTPs) over an 11-month period.  $\text{NH}_4^+$  data were collected with ion-selective sensors. The model performance evaluation focused on applications in relation to online control strategies. The results of the monitoring campaigns highlighted a high variability in daily  $\text{NH}_4^+$  profiles, stressing the importance of an uncertainty-based modelling approach. The maintenance of the  $\text{NH}_4^+$  sensors resulted in important variations of the

Luca Vezzaro<sup>IWA</sup> (corresponding author)  
Krüger A/S, Veolia Water Technologies,  
Gladsaxevej 363, 2860 Søborg,  
Denmark  
E-mail: [luve@env.dtu.dk](mailto:luve@env.dtu.dk)

Luca Vezzaro  
Jonas Wied Pedersen  
Laura Holm Larsen  
Peter Steen Mikkelsen<sup>IWA</sup>  
Department of Environmental Engineering (DTU  
Environment),  
Technical University of Denmark,  
Building 115, 2800 Kongens Lyngby,  
Denmark

Article available at (subscription):

<https://www.sciencedirect.com/science/article/pii/S0043135420307648>

Or get a copy by sending Jonas a request via LinkedIn or email:

[jowi@env.dtu.dk](mailto:jowi@env.dtu.dk)

<https://www.linkedin.com/in/jonaswied/>

Article freely available at:

<https://iwaponline.com/wst/article/81/1/109/72455/Evaluating-the-performance-of-a-simple>

DTU

